

## Stellaris<sup>®</sup> LM3S3Z26 RevB1 Errata

This document contains known errata at the time of publication for the Stellaris<sup>®</sup> LM3S3Z26 microcontroller. The table below summarizes the errata and lists the affected revisions. See the data sheet for more details.

See also the ARM<sup>®</sup> Cortex<sup>™</sup>-M3 errata, ARM publication number PR326-PRDC-009450 v2.0.

Erratum Number	Erratum Title	Revision(s) Affected
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8.1	An interrupt is not generated when using $\mu$ DMA with the SSI module if the EOT bit is set	B1
9.1	USB0ID and USB0VBUS signals are required to be connected regardless of mode	B1

Erratum Number	Erratum Title	Revision(s) Affected
9.2	Latch up may occur if power is applied to the VBUS pin but not to VDD	B1
10.1	Power-on event may disrupt operation	B1
10.2	Momentarily exceeding $V_{IN}$ ratings on any pin can cause latch-up	B1

# 1 JTAG

## 1.1 JTAG INTEST instruction does not work

### Description:

The JTAG INTEST (Boundary Scan) instruction does not properly capture data.

### Workaround:

None.

### Silicon Revision Affected:

B1

### Fixed:

Fixed in Rev C.

## 1.2 The Recover Locked Device sequence does not work

### Description:

If software configures any of the JTAG/SWD pins as GPIO or loses the ability to communicate with the debugger, there is a debug sequence that can be used to recover the microcontroller, called the Recover Locked Device sequence. After reconfiguring the JTAG/SWD pins, using the Recover Locked Device sequence does not recover the device.

### Workaround:

To get the device unlocked, follow these steps:

1. Power cycle the board and run the debug port unlock procedure in LM Flash Programmer. DO NOT power cycle when LM Flash Programmer tells you to.
2. Go to the Flash Utilities tab in LM Flash Programmer and do a mass erase operation (check "Entire Flash" and then click the Erase button). This erase appears to have failed, but that is ok.
3. Power cycle the board.
4. Go to the Flash Utilities tab in LM Flash Programmer and do another mass erase operation (check "Entire Flash" and then click the Erase button).

### Silicon Revision Affected:

B1

**Fixed:**

Not fixed in Rev C.

## 2 System Control

### 2.1 Hard Fault possible when waking from Sleep or Deep-Sleep modes and Cortex-M3 Debug Access Port (DAP) is enabled

**Description:**

If the Cortex-M3 Debug Access Port (DAP) has been enabled, and the device wakes from a low power sleep or deep-sleep mode, the core may start executing code before all clocks to peripherals have been restored to their run mode configuration. The DAP is usually enabled by software tools accessing the JTAG or SWD interface when debugging or flash programming. If this condition occurs, a Hard Fault is triggered when software accesses a peripheral with an invalid clock.

**Workaround:**

A software delay loop can be used at the beginning of the interrupt routine that is used to wake up a system from a WFI (Wait For Interrupt) instruction. This stalls the execution of any code that accesses a peripheral register that might cause a fault. This loop can be removed for production software since the DAP is most likely not enabled during normal execution.

Since the DAP is disabled by default (power on reset), the user can also power cycle the device. The DAP will not be enabled unless it is enabled through the JTAG or SWD interface.

**Silicon Revision Affected:**

B1

**Fixed:**

Will not be fixed.

### 2.2 Sleep and Deep-Sleep mode not usable at higher speeds when ISRs reside in Flash memory

**Description:**

Sleep and Deep-Sleep modes cannot be used when running the processor at 66 or 80 MHz when the ISRs and vector table reside in Flash memory. If Sleep or Deep-Sleep mode is used at those speeds, an invalid PC is sometimes returned for the interrupt vector address when exiting sleep mode.

**Workaround:**

There are two possible workarounds for this issue:

1. Store the ISRs and vector table in the on-chip SRAM when running the processor at 66 or 80 MHz.
2. Run the processor at 50 MHz.

**Silicon Revision Affected:**

B1

**Fixed:**

Fixed in Rev C.

## 2.3 Device Capabilities registers may not accurately reflect available signals

**Description:**

Some of the Device Capabilities register bits reflect the presence of specific pins on the microcontroller. These bits do not always properly reflect the available signals. Bits affected include **DC3** [31:0], **DC4** [15:14], **DC5** [27:24] and [7:0], and **DC8** [31:0]. Do not rely on the value of these bits in system design.

**Workaround:**

None.

**Silicon Revision Affected:**

B1

**Fixed:**

Fixed in Rev C.

## 2.4 The PIOSC is not trimmed by the factory

**Description:**

The PIOSC is not trimmed by the factory prior to shipment.

**Workaround:**

For parts that have a Hibernation module, the PIOSC can be user calibrated.

**Silicon Revision Affected:**

B1

**Fixed:**

Fixed in Rev C.

## 2.5 The CLASS field in Device Identification 0 (DID0) register is incorrect

**Description:**

The **CLASS** field, bits[23:16], in the **Device Identification 0 (DID0)** register is incorrect. The **CLASS** field should be 0x04 indicating the Stellaris Tempest class of microcontrollers. Instead, the field reads as 0x03.

**Workaround:**

None.

**Silicon Revision Affected:**

B1

**Fixed:**

Not fixed in Rev C.

## 3 Hibernation Module

### 3.1 Hibernation module may have higher current draw than specified in data sheet under certain conditions

**Description:**

If a battery voltage is applied to the  $V_{BAT}$  power pin prior to power being applied to the  $V_{DD}$  power pins of the device, the current draw from the  $V_{BAT}$  pin is greater than expected. The current may be as high as 1.6 mA instead of the data sheet specified 17  $\mu$ A. The condition exists until power is applied to the  $V_{DD}$  pin. Once the  $V_{DD}$  pin has been powered, the  $V_{BAT}$  current draw functions as expected. The  $V_{DD}$  pin can then be powered up and down as required and the  $V_{BAT}$  pin current specification is maintained.

**Workaround:**

The  $V_{BAT}$  pin higher-than-specified current draw condition can be avoided if the microcontroller's  $V_{DD}$  power pins are powered on prior to the time a battery voltage is initially applied to the  $V_{BAT}$  pin.

**Silicon Revision Affected:**

B1

**Fixed:**

Fixed in Rev C.

### 3.2 Hibernate POR may not reset the Hibernation module until $V_{DD}$ is applied

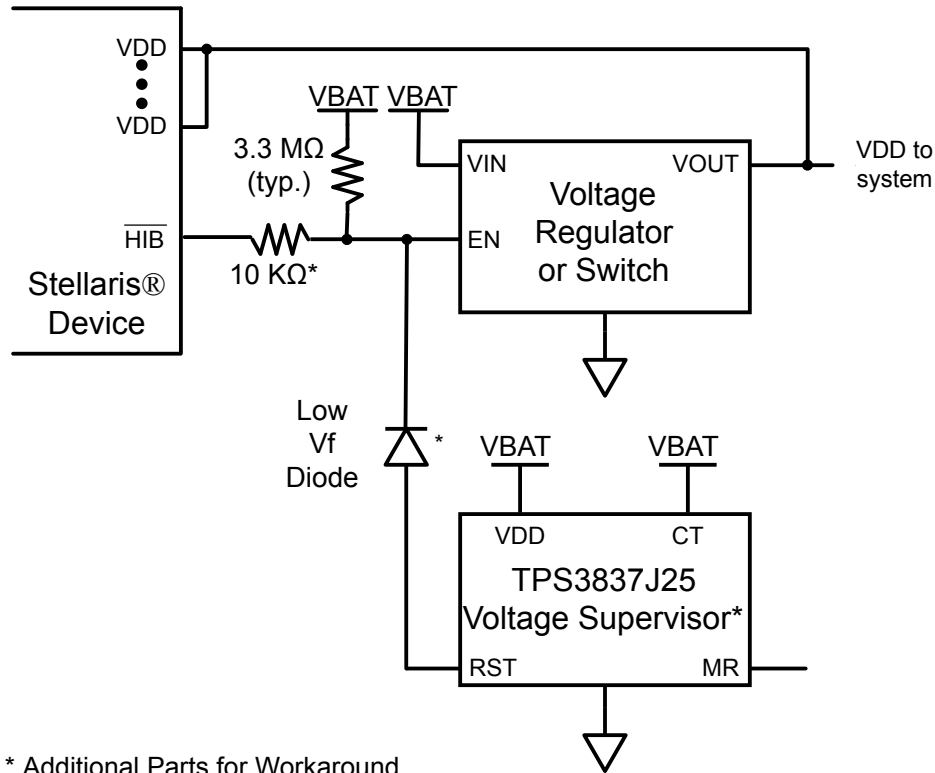
**Description:**

If  $V_{DD}$  is not powered when voltage is first applied to  $V_{BAT}$ , the state of the Hibernation module is indeterminate and the  $\overline{HIB}$  signal may be asserted. In this indeterminate state, a lock condition can occur in which the Hibernation module waits for a power-on-reset, but that reset cannot occur until the module deasserts  $\overline{HIB}$ . This issue is related to the errata "Hibernation module may have higher current draw than specified in data sheet under certain conditions" on page 5.

**Workaround:**

The workaround implementation depends on the system-level power supply configuration. For systems that use a battery as the primary power source, an external voltage supervisor (TPS383J25DBV or similar) circuit can be added to force the  $V_{DD}$  power supply to start when the battery voltage is first applied (see Figure 1). The voltage supervisor requires only 220 nA and generates a 200-ms positive pulse to turn on the  $V_{DD}$  regulator and activate the microcontroller's internal POR circuit.

Figure 1. Workaround Circuit to Ensure Initial Power Up

**Silicon Revision Affected:**

B1

**Fixed:**

Fixed in Rev C.

**3.3 Power consumption increases if  $V_{DD}$  is not restored after wake from hibernation****Description:**

If a wake event occurs and  $V_{DD}$  does not rise to specified levels, then the wake event is held off until  $V_{DD}$  is within specified levels. If a large delay occurs between the wake event and  $V_{DD}$  reaching specified levels, the  $V_{BAT}$  current increases substantially to a typical value of 255  $\mu\text{A}$  until  $V_{DD}$  reaches the specified levels, at which point the microcontroller comes out of hibernation and power consumption returns to expected levels.

**Workaround:**

Ensure that  $V_{DD}$  reaches specified levels within 250  $\mu\text{s}$  after the wake event occurs.

**Silicon Revision Affected:**

B1

**Fixed:**

Fixed in Rev C.

### 3.4 ESD protection on the $V_{BAT}$ pin does not meet specifications

**Description:**

The ESD protection on the  $V_{BAT}$  pin fails when tested at 2 kV.

**Workaround:**

Extra precaution should be taken to protect the part from ESD events. Some applications may require system-level ESD protection on this pin.

**Silicon Revision Affected:**

B1

**Fixed:**

Fixed in Rev C.

### 3.5 Use of the VDD3ON mode to initiate hibernation damages the part

**Description:**

The VDD3ON mode is enabled by setting the  $VDD3ON$  bit in the **Hibernation Control (HIBCTL)** register. Permanent damage can occur to the device if this mode is used.

**Workaround:**

Do not use the VDD3ON mode to enter hibernation, instead use an external switch or regulator to manage  $V_{DD}$  power to the device.

**Silicon Revision Affected:**

B1

**Fixed:**

Fixed in Rev C.

### 3.6 Hibernate module power consumption higher than expected in event wakeup configuration

**Description:**

With the Hibernation module configured for an external event wakeup, the current consumption of the device is higher than expected. The Hibernation module clock does not shut down properly during the hibernate asynchronous external wake mode resulting in extra current consumption. Some devices properly shut down the clock the first time entering this mode and others do not. When waking from a hibernate event, the Hibernation module clock is always enabled. In subsequent hibernate cycles, the oscillator is not shut down properly and remains active. Hibernate module current consumption averages  $21\mu A$  with the clock disabled. The current consumption averages  $31\mu A$  with the Hibernation module clock enabled.

**Workaround:**

When the Hibernation module clock is not required during hibernation, software can disable it by clearing the `CLK32EN` bit in the **Hibernation Control (HIBCTL)** register before going into hibernation mode.

**Silicon Revision Affected:**

B1

**Fixed:**

Fixed in Rev C.

### 3.7 The Real-Time Clock gains or loses time going in and out of hibernation when using a crystal

**Description:**

When using a 4.194304-MHz crystal, the Real-Time clock in the Hibernation module gains or loses a small amount of time (on the order of one second over a 24-hour period when cycling hibernate mode 4 times a minute) when going in and out of hibernation.

**Workaround:**

Use an external 32.768-kHz oscillator as the source for the Hibernation module clock.

**Silicon Revision Affected:**

B1

**Fixed:**

Fixed in Rev C.

### 3.8 Low-battery detect circuit is powered down during hibernate

**Description:**

The low-battery detect feature on the  $V_{BAT}$  input is only valid when  $V_{DD}$  power is present. As a result:

- Because the battery is not electrically loaded when  $V_{DD}$  is present, the low-battery detect circuit may not reflect the actual battery status.
- In Hibernate mode, a low-battery condition may prevent wake until the battery is completely depleted.

**Workaround:**

None.

**Silicon Revision Affected:**

B1

**Fixed:**

Fixed in Rev C.



## 4 Internal Memory

### 4.1 Cumulative page erases may introduce bit errors in Flash memory

**Description:**

Cumulative page erases anywhere in the Flash memory array may introduce bit errors. The bit error is not confined to the page being erased or the 4-KB block but could be in any page in the Flash memory. A page erase is used to erase a 1-KB page so it can be rewritten. A mass erase erases the entire Flash memory array (all pages). A bit error means that a bit may change from 0 to 1 or 1 to 0.

**Workaround:**

There are two possible workarounds for this issue:

1. Minimize total page erases to less than 3000 between mass erases for the lifetime of the product. After each mass erase, an additional 3000 page erase operations are allowed before bit errors may be introduced. At the rate of one page erase per week, this issue would not be seen over at least 17 years.
2. Perform CRC checks on all Flash memory after page erases to increase the chances of detecting the issue. The two CRC functions built into ROM can assist in this.

**Silicon Revision Affected:**

B1

**Fixed:**

Fixed in Rev C.

## 5 ROM

### 5.1 Some ROM functions are unsupported

**Description:**

The following functions are unsupported in ROM:

- GPIOPinConfigure
- GPIOPinTypeI2S
- I2CSlaveIntClearEx
- I2CSlaveIntDisableEx
- I2CSlaveIntEnableEx
- I2CSlaveIntStatusEx
- I2SRxDisable
- SysCtlDelay
- UARTBusy
- UARTFIFODisable
- UARTFIFOEnable
- UARTRxErrorClear
- UARTRxErrorGet
- UARTTxIntModeGet
- UARTTxIntModeSet
- uDMAChannelSelectDefault

- uDMAChannelSelectSecondary
- USBDevEndpointConfigGet
- USBEndpointDataAvail
- USBEndpointDMAChannel
- USBEndpointDMADisable
- USBEndpointDMAEnable
- USBModeGet
- USBOTGHostRequest

**Workaround:**

Code for these functions is included in the current version of StellarisWare, which can be downloaded from the website at [http://www.luminarymicro.com/products/software\\_updates.html](http://www.luminarymicro.com/products/software_updates.html).

**Silicon Revision Affected:**

B1

**Fixed:**

Fixed in Rev C.

## 5.2 ROM mapping check for the Boot loader does not function properly

**Description:**

Before the processor is released from the reset state, the System Control module is supposed to check offset 0x0000.0004 of Flash memory looking for a reset vector that is not 0xFFFF.FFFF. If an initialized reset vector is found, Flash memory is mapped to address 0x0000.0000, otherwise ROM is mapped to address 0x0000.0000. Currently, the System Control module errantly checks offset 0x0000.0008, which is the NMI vector. So, in situations where a valid reset vector (offset 0x0000.0004) has been programmed, but the NMI vector has not been programmed, the ROM is errantly mapped to zero preventing the application that is stored in Flash memory from being executed out of reset.

**Workaround:**

Ensure that the NMI vector is always programmed.

**Silicon Revision Affected:**

B1

**Fixed:**

Not fixed in Rev C.

## 6 GPIO

### 6.1 Port B [1:0] pins require external pull-up resistors

**Description:**

The internal pull-up resistors are not effective for the Port B0 and B1 pins.

**Workaround:**

External pull-up resistors must be used on these two pins.

**Silicon Revision Affected:**

B1

**Fixed:**

Fixed in Rev C.

## 7 UART

### 7.1 UART Smart Card (ISO 7816) mode does not function

**Description:**

The `UnTX` signal does not function correctly as the bit clock in Smart Card mode.

**Workaround:**

None.

**Silicon Revision Affected:**

B1

**Fixed:**

Fixed in Rev C.

### 7.2 When in IrDA mode, the UnRx signal requires configuration even if not used

**Description:**

When in IrDA mode, the transmitter may not function correctly if the `UnRx` signal is not used.

**Workaround:**

When in IrDA mode, if the application does not require the use of the `UnRx` signal, the GPIO pin that has the `UnRx` signal as an alternate function must be configured as the `UnRx` signal and pulled High.

**Silicon Revision Affected:**

B1

**Fixed:**

Fixed in Rev C.

## 8 SSI

### 8.1 An interrupt is not generated when using $\mu$ DMA with the SSI module if the EOT bit is set

**Description:**

When using the primary  $\mu$ DMA channels with the SSI module, an interrupt is not generated on transmit  $\mu$ DMA completion if the `EOT` bit (bit 4 of the `SSICR1` register) is enabled.

**Workaround:**

Use the alternate  $\mu$ DMA channels for the SSI module.

**Silicon Revision Affected:**

B1

**Fixed:**

Fixed in Rev C.

## 9 USB

### 9.1 USB0ID and USB0VBUS signals are required to be connected regardless of mode

**Description:**

The `DEVMODOTG` bit in the **USB General-Purpose Control and Status (USBGPCS)** register does not function correctly.

**Workaround:**

Connect the `USB0VBUS` input to `VBUS` in all modes. In addition, connect the `USB0ID` pin to ground for Host mode operation and to `VDD` for Device mode operation using the `DEVMOD` bit in the **USB General-Purpose Control and Status (USBGPCS)** register.

**Silicon Revision Affected:**

B1

**Fixed:**

Fixed in Rev C.

### 9.2 Latch up may occur if power is applied to the `VBUS` pin but not to `VDD`

**Description:**

If power is applied to the `VBUS` pin but not to `VDD`, the microcontroller may latch up and or draw excessive current. This condition can occur if the microcontroller is unpowered and is connected as a USB device or OTG B.

**Workaround:**

Power up the microcontroller before attaching the USB cable. Also, the USB cable must be detached before powering down the microcontroller.

**Silicon Revision Affected:**

B1

**Fixed:**

Fixed in Rev C.

## 10 Electrical Characteristics

### 10.1 Power-on event may disrupt operation

#### Description:

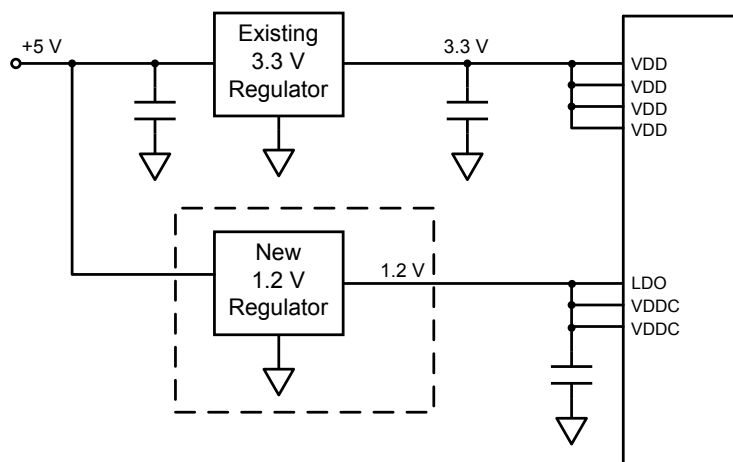
Incorrect power sequencing during power up can disrupt operation and potentially cause device failure.

#### Workaround:

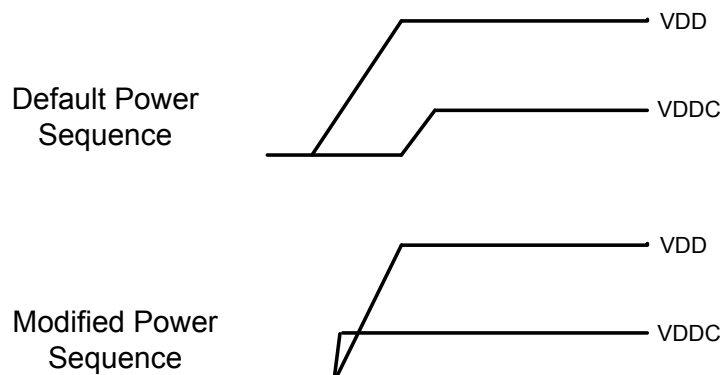
$V_{DDC}$  must be applied approximately 50  $\mu$ s before  $V_{DD}$ . Normally  $V_{DDC}$  is controlled by the part's internal LDO voltage regulator. The workaround requires the addition of an external regulator (see Figure 2) to ensure that  $V_{DDC}$  sequencing requirements are met (see Figure 3). Recommended regulators include FAN1112SX (SOT223) and FAN2558S12X (SOT23-5).

This fix mitigates the on-chip power issue, but does not solve it completely. During development, the Flash memory should also be reprogrammed (using LMflash or another programming tool) at least once a week.

**Figure 2. Configuration of External Regulator**



**Figure 3. VDDC Sequencing Requirements**



Detailed characterization is ongoing. Contact the Applications Support Team for the latest information.

**Silicon Revision Affected:**

B1

**Fixed:**

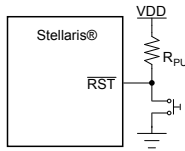
Fixed in Rev C.

## 10.2 Momentarily exceeding $V_{IN}$ ratings on any pin can cause latch-up

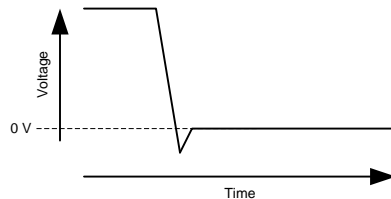
**Description:**

To avoid latch-up, the maximum DC ratings of the part must be strictly enforced. The most common violation of the  $V_{IN}$  electrical specification can occur when a mechanical switch or contact is connected directly to a GPIO or special function ( $\overline{RST}$ ,  $\overline{WAKE}$ , ...) pin. The circuit shown in Figure 4 on page 14 typically has stray inductance and capacitance that can cause a voltage glitch when the switch transitions, as shown in Figure 5 on page 14. The magnitude of the glitch may exceed the  $V_{IN}$  in the maximum DC ratings table in the Electrical Characteristics chapter. Figure 6 on page 15 shows an improved circuit that eliminates the glitch.

**Figure 4. Incorrect Reset Circuitry**



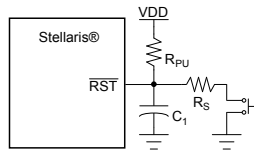
**Figure 5. Excessive Undershoot Voltage on Reset**



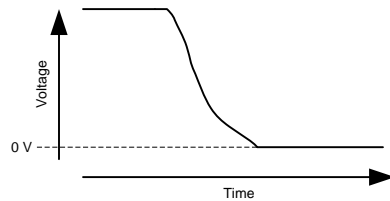
**Workaround:**

Use a circuit as shown in Figure 6 on page 15. In this circuit,  $R_S$  should be less than or equal to  $R_{PU}/10$ .  $C_1$  should be matched to  $R_{PU}$  to achieve a suitable  $t_{RC}$  for the application. Typical values are:

- $R_{PU} = 10 \text{ k}\Omega$
- $R_S = 470 \text{ }\Omega$
- $C_1 = 0.01 \text{ }\mu\text{F}$

**Figure 6. Recommended Reset Circuitry**

After implementing the circuit shown in Figure 6 on page 15, confirm that the voltage on the  $\overline{\text{RST}}$  input has a curve similar to the one in Figure 7 on page 15, and that the  $V_{\text{IN}}$  specification is not exceeded.

**Figure 7. Recommended Voltage on Reset****Silicon Revision Affected:**

B1

**Fixed:**

Fixed in Rev C.

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DSP	<a href="http://dsp.ti.com">dsp.ti.com</a>
Clocks and Timers	<a href="http://www.ti.com/clocks">www.ti.com/clocks</a>
Interface	<a href="http://interface.ti.com">interface.ti.com</a>
Logic	<a href="http://logic.ti.com">logic.ti.com</a>
Power Mgmt	<a href="http://power.ti.com">power.ti.com</a>
Microcontrollers	<a href="http://microcontroller.ti.com">microcontroller.ti.com</a>
RFID	<a href="http://www.ti-rfid.com">www.ti-rfid.com</a>
RF/IF and ZigBee® Solutions	<a href="http://www.ti.com/lprf">www.ti.com/lprf</a>

### Applications

Audio	<a href="http://www.ti.com/audio">www.ti.com/audio</a>
Automotive	<a href="http://www.ti.com/automotive">www.ti.com/automotive</a>
Broadband	<a href="http://www.ti.com/broadband">www.ti.com/broadband</a>
Digital Control	<a href="http://www.ti.com/digitalcontrol">www.ti.com/digitalcontrol</a>
Medical	<a href="http://www.ti.com/medical">www.ti.com/medical</a>
Military	<a href="http://www.ti.com/military">www.ti.com/military</a>
Optical Networking	<a href="http://www.ti.com/opticalnetwork">www.ti.com/opticalnetwork</a>
Security	<a href="http://www.ti.com/security">www.ti.com/security</a>
Telephony	<a href="http://www.ti.com/telephony">www.ti.com/telephony</a>
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